

$T_c \geq 10 \text{ ms} = T_s/2$
recommended

$T_{\text{Bus}} = T_s / 2 !$

Overall cycle
 $= T_c + \max[T_s, T_m]$

CANopen (62,5 kBd ... 1 MBd)

T_s
Type 1: $\leq 20 \text{ ms} / \text{module}$
Type 2: $\leq 10 \text{ ms} / \text{module}$

Internal bus (500 kBd, cyclic)

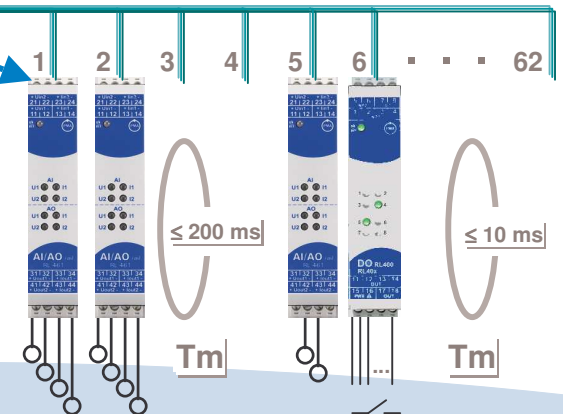


Communication

| Node | Baud rate |
|------|-------------------------|
| 1 | $\geq 62,5 \text{ kBd}$ |
| 2 | $\geq 125 \text{ kBd}$ |
| 4 | $\geq 250 \text{ kBd}$ |
| 8 | $\geq 500 \text{ kBd}$ |
| 16 | $\geq 1 \text{ MBd}$ |

CAN node

RL40
CANopen



Type 1
AI
2/4 channels

Type 2
AO 2 channels
DI / DO 8 channels

Remarks

- ✓ Analogue values are transferred as **Float format** !
- ✓ Cycle times are valid for max. 62 module per node !
- ✓ Cycles T_c , T_s and T_m run asynchronous !
- ✓ The CAN bus communication is deterministic ! The cycle is determined by adjusted T_c of the FB's.
- ✓ Recommended: $T_c \geq 10 \text{ ms} = T_s/2$

